

**2023****M.Sc.****4th Semester Examination****ELECTRONICS****PAPER : ELC-403***Full Marks : 50**Time : 2 hours*

*The figures in the right-hand margin indicate marks.*

*Candidates are required to give their answers in their own words as far as practicable.*

*Illustrate the answers wherever necessary.*

Answer **all** questions.

**( CONTROL SYSTEM AND INSTRUMENTATION )**

1. Answer **any four** questions from the following :  
2×4=8

(a) Open-loop transfer function of a control system is given by  $G(S) = \frac{5}{(S+3)}$  and

$H(S) = \frac{3}{(S+5)}$ . Determine the characteristic equation. 2

( 2 )

(b) Depending upon the  $\xi$ , mention the different damping systems. 2

(c) Open-loop transfer function of a control system is given by  $G(S) = \frac{k}{(1+ST_1)(1+ST_2)}$ .

Draw the polar plot of the system. 2

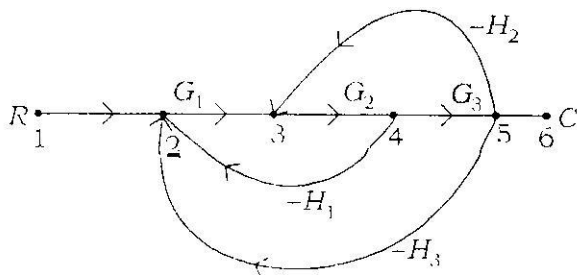
(d) Differentiate between Mason's gain formulas and block diagram reduction method. 2

(e) Mention two applications of spectrum analyzer. 2

(f) Define phase margin and gain margin of a control system. 2

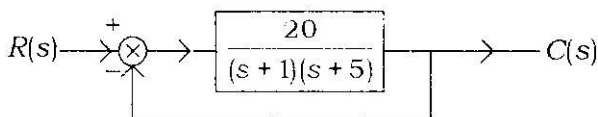
2. Answer *any four* questions from the following :  
4×4=16

(a) Find  $e/R$  of the following SFG using Mason's gain formula : 4



( 3 )

- (b) The block diagram of a unity feedback control system is shown below :

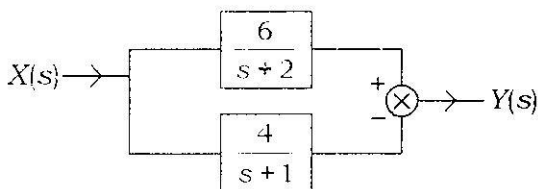


Determine the characteristic equation of the system  $t_p$  and  $M_p$ . 2+2=4

- (c) The open-loop transfer function of a unity feedback system is given by

$G(S) = \frac{50}{(1+0.1S)(S+10)}$ . Determine static error coefficients  $K_p$  and  $K_v$ . 2+2=4

- (d) Show that the transfer function  $Y(s)/X(s)$  has a zero in the right half  $s$  plane. Obtain  $Y(t)$  when  $X(t)$  is a unit step for the system shown below : 4



- (e) Sketch the Bode plot of the system 4

$$G(S) = \frac{1}{(S+3)^3}$$

( 4 )

(f) Differentiate between active and passive transducers. What are the advantages of semiconductor strain gauge?  $2+2=4$

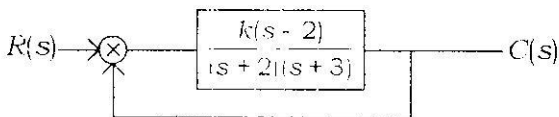
3. Answer *any two* questions from the following :  $8 \times 2 = 16$

(a) The characteristic equation of a feedback control system is given below :

$$S^4 + 25S^3 + 15S^2 + 20S + K = 0$$

Determine the range of  $K$  for stability. Determine the value of  $K$  so that the system is marginally stable and find the frequency of sustained oscillations.  $4+2+2=8$

(b) For the system shown below, sketch the Nyquist plot for  $K=2$  and use the Nyquist criteria to determine whether the closed loop system is stable for this gain. Find the range of  $K$  for the system to be stable.  $6+2=8$



(c) Explain function generator using block diagram.  $8$

(d) Sketch the root locus plot for the system having open-loop transfer function given by

$$G(S)H(S) = \frac{k}{S(S+4)(S^2+4S+13)} \quad 8$$

[ Internal Assessment : 10 Marks ]

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