

**2015**

**M.A. / M.Sc.**

**1st Semester Examination**

**ECONOMICS**

**PAPER—ECO-104**

*Full Marks : 40*

*Time : 2 Hours*

*The figures in the right-hand margin indicate full marks.*

*Candidates are required to give their answers in their own words as far as practicable.*

*Illustrate the answers wherever necessary.*

**Group—A**

1. Answer any two questions of the following : 2×2

(a) Explain the difference between linear and non linear programming problem.

(b) Find the solution of the inequality :

$$S_1 = \left\{ x : 2x - 6 > 0 \text{ and } -1 \leq \frac{x+3}{2x-6} \leq 1 \right\}$$

*(Turn Over)*

- (c) What Surjective function ?
- (d) Give an example of an equal function.

2. Answer any *one* question of the following : 1×6

- (a) Explain the statement that "Boundary irregularities will not occur if a Certain Constraint qualification is Satisfied". 6
- (b) Compare between the Kuhn-Tucker sufficiency Theorem and The Arrow-Enthoven Sufficiency Theorem. 6

3. Answer any *one* question of the following : 1×10

- (a) Derive the Kuhn-Tucker Condition for a maximisation problem.
- (b) Solve the following minimization problem :

$$\text{Minimize } C = (x_1 - 4)^2 + (x_2 - 4)^2$$

$$\text{Subject to } 2x_1 + 3x_2 \geq 6$$

$$- 3x_1 - 2x_2 \geq - 12$$

$$\text{and } x_1, x_2 \geq 0$$

**Group—B**

4. Answer any *two* questions of the following : 2×2
- (a) What do you mean by repeated game. Give example.
  - (b) Which kind of Nash equilibrium can be eliminated by backward induction ?
  - (c) Distinguish between function and functional.
  - (d) What is current valued Hamiltonian ?
5. Answer any *one* question of the following : 1×6
- (a) Define Nash equilibrium. Explain the problems associated with it.
  - (b) Using a two variable model illustrate the concept of phase diagram.
6. Answer any *one* question : 1×10
- (a) Present the problem of Prisoners Dilemma. Show how does the 'co-operation' possible for an infinitely repeated Prisoners Dilemma game. 4+6

- (b) What is Hamiltonian function? Write the conditions to obtain optimal solution path for the control variable. Find the optimal paths of control, state and costate variables for the following problem.

$$\text{Max} \int_0^T -(t^2 + u^2) dt$$

$$\text{s. t. } \dot{y} = u$$

$$\text{and } y(0) = 4, y(T) = 5, T \text{ free.}$$

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