

M.Sc. 2nd Semester Examination, 2015

APPLIED MATHEMATICS WITH OCEANOLOGY  
AND COMPUTER PROGRAMMING

( *Numerical Analysis* )

PAPER — MTM - 202

*Full Marks : 50*

*Time : 2 hours*

Answer Q.No.1 and any two from the rest

*The figures in the right-hand margin indicate marks*

1. Answer any *four* questions : 2 × 4

(a) Prove that

$$(1 + \delta^2 \mu^2) f(x) = \left(1 + \frac{\delta^2}{2}\right)^2 f(x),$$

where the symbols have their usual meanings.

( Turn Over )

- (b) What is meant by ill-conditioned system of Linear algebraic equations ?
- (c) What are the similarities and dissimilarities between modified Euler's method and second order Runge-Kutta method ?
- (d) Compare direct and iterative method to solve a system of linear equations.
- (e) What is the advantage to use the Tchebyshev Polynomials to approximate a function ?
- (f) Obtain the approximate quadrature formula

$$\int_{-1}^1 f(x) dx = \frac{1}{9} \left[ 5f(-\sqrt{0.6}) + 8f(0) + 5f(\sqrt{0.6}) \right]$$

2. (a) Explain Milne's predictor-corrector formula to solve the differential equation

$$\frac{dy}{dx} = f(x, y), \quad y(x_0) = y_0.$$

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- (b) Explain Runge-kutta fourth order method to solve the following system of differential equations

$$\frac{dy}{dx} = f(x, y, z), \quad \frac{dz}{dx} = g(x, y, z)$$

with  $y(x_0) = y_0$  and  $z(x_0) = z_0$ . 2

- (c) Use Newton-Raphson method to find a root of the system  $x^2 - 2x - y + 0.5 = 0$ ,  $x^2 + 4y^2 - 4 = 0$  with the starting value  $(x_0, y_0) = (2.0, 0.25)$ , correct up to four decimal places. 6

3. (a) Explain finite difference method to solve the following equation

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}, \quad t > 0, \quad 0 < x < 1.$$

with initial conditions

$$u(x, 0) = f(x), \quad u_t(x, 0) = g(x), \quad 0 < x < 1$$

and boundary conditions

$$u(0, t) = \phi(t), \quad u(1, t) = \psi(t), \quad t \geq 0. \quad 8$$

(b) Suppose

$$y = 1 - \frac{x}{2!} + \frac{x^2}{4!} - \frac{x^3}{6!} + \frac{x^4}{8!} - \dots$$

Economize this series if the fourth decimal place is not to be affected, near  $x = 1$ . 4

(c) Explain partial pivoting method to find the inverse of a square non-singular matrix. 4

4. (a) Deduce three-point Gauss-Legendre quadrature formula. 4

(b) Discuss the stability of second order Runge-Kutta method. 4

(c) Describe power method to find the largest (in magnitude) eigen-value and the corresponding eigen-vector of a matrix. Can this method be used to find the least eigen-value? Explain. 6 + 2

[ *Internal Assessment* : 10 Marks ]