#### 2017

### M.Sc. 2nd Semester Examination

# APPLIED MATHEMATICS WITH OCEANOLOGY AND COMPUTER PROGRAMMING

#### PAPER-MTM-202

Full Marks: 50

Time: 2 Hours

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable.

Illustrate the answers wherever necessary.

## (Numerical Analysis)

Answer Q. No. 1 and any two from the rest.

## 1. Answer any four questions:

2×4

(a) Consider the function

$$f(x) = \begin{cases} -\frac{11}{2}x^3 + 26x^2 - \frac{75}{2}x + 18, & 1 \le x \le 2\\ \frac{11}{2}x^3 - 40x^2 + \frac{189}{2}x - 70, & 2 \le x \le 3 \end{cases}$$

Show that f(x) is a cubic spline.

- (b) Compare Gausian quadrature and Monte-Carlo method to find integration.
- (c) What are the advantages to approximate a function using orthogonal polynomials?
- (d) Explain the importance of weighted curve fitting.
- (e) Discuss the merits and demerits of finite difference method to solve an ordinary differential equation.
- (f) What is the advantage of successive over relaxation method over Gauss-Seidal iteration method to solve a system of linear equations?
- (a) Suppose a table of values (x<sub>i</sub>, y<sub>i</sub>), i = 0, 1, 2, ..., n, is given. Describe natural cubic spline method to fit this set of data.
  - (b) Economize the power series

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \frac{x^8}{8!} - \cdots$$

correct up to four significant figures.

- 3. Answer any two equations:
  - (a) Describe power method to find largest eigenvalue and corresponding eigen vector of a matrix. When does the method fail?
    7+1
  - (b) Describe Milne's method to solve the following differential equation:

$$\frac{dy}{dx} = f(x,y), \ y(x_0) = y_0.$$
 8

(c) Describe 3-point Gauss-Legendre quadrature formula.

Use this formula to find the value of

$$\int_0^2 \left( x^5 + 2x^2 + 3x \right) dx$$
 4+4

**4.** (a) Describe the Crank-Nicolson implicit method to solve the following equation :

$$\frac{\partial \mathbf{u}}{\partial \mathbf{t}} = \alpha \frac{\partial^2 \mathbf{u}}{\partial \mathbf{x}^2}$$

subject to the boundary conditions  $u(0, t) = f_1(t)$ ,  $u(1, t) = f_2(t)$  and the initial condition u(x, 0) = g(x).

(b) Describe LU-decomposition method to solve a system of linear equations.

| Internal Assessment -10 |